

## Lecture 7

### Calculation of curvilinear integrals

We restrict to the case of 2D plane  $\mathbb{R}^2$ .

Let we have a curve  $L$ :

$$L = \{ (x, y) \mid x = x(s), y = y(s) \},$$

where  $s$  is the arc-length of the curve.

Let  $F(x, y)$  be a function defined on  $L$  (e.g. a density of the mass)

Definition . The curvilinear integral is defined by the equality

$$\int_L F(x, y) ds \stackrel{\text{def}}{=} \int_0^s F(x(s), y(s)) ds.$$

It is called a line integral of the first kind.

The definition is described in terms of Riemann sums. This approach gives conditions to define a set of  $F(x, y)$  and  $L$  which are Riemann-integrable.

1. Define a partition  $\tau$  of  $L$  for  $s \in [0, S]$ ,  $\{s_i : i = 0, 1, \dots, m\}$

$\Delta s_i = s_i - s_{i-1}$  is the length of the section of  $L$  from the point  $(x(s_{i-1}), y(s_{i-1}))$  to the point  $(x(s_i), y(s_i))$ .

$$\delta_{\tau} = \max_{1 \leq i \leq m} \Delta s_i$$

2. Next we select  $\xi_i \in [s_{i-1}, s_i]$   
a sample point

3. A Riemann sum is defined by

$$S_{\tau} \stackrel{\text{def}}{=} \sum_{i=1}^m F(x(\xi_i), y(\xi_i)) \Delta s_i$$

Def.

$$\int_C F(x, y) ds = \lim_{\delta_{\tau} \rightarrow 0} S_{\tau}$$

if this limit do not depend on mesh  $\tau$  and sample points  $\xi_i$ .

If curve  $L$  is defined in 3D space and  $F(x, y, z)$  is a smooth function then

$$\int_L F(x, y, z) ds = \lim_{\epsilon \rightarrow 0} \sum_{i=1}^n F(x_i, y_i, z_i) \Delta s_i$$

### Calculation of integrals.

We calculated in previous lectures how the length of curve like is expressed.

Let us assume that  $L$  is defined ~~as~~ in plane  $xOy$  by

$$y = y(x), \quad a \leq x \leq b.$$

Then

$$\Delta s_i \approx \sqrt{1 + (y'(x))^2} \Delta x_i$$

$$\sigma_z = \sum_{i=1}^n F(x_i, y_i) \sqrt{1 + (y'(x_i))^2} \Delta x_i$$

Taking a limit  $\sigma_z = \max \Delta x_i \rightarrow 0$   
we get

$$\int_L F(x, y) ds = \int_a^b F(x, y(x)) \sqrt{1 + (y'(x))^2} dx$$

If  $L$  is defined by parametric equations

$$x = x(t), \quad y = y(t), \quad t \in [c, d]$$

then

$$\int_L F(x, y) ds = \int_c^d F(x(t), y(t)) \sqrt{(x'_t)^2 + (y'_t)^2} dt$$

$ds = \sqrt{(x'_t)^2 + (y'_t)^2} dt$   
3D space

If  $L$  is defined in

$$x = x(t), \quad y = y(t), \quad z = z(t), \quad t \in [c, d]$$

-5-

then the curvilinear integral is calculated by the formula

$$\int_L F(x, y, z) ds = \int_c^d F(x(t), y(t), z(t)) \sqrt{x_t^2 + y_t^2 + z_t^2} dt$$

Remark. This integral of first kind does not depend on the orientation of the curve  $L$ .

$$\int_{AB} F(x, y) ds = \int_{BA} F(x, y) ds$$

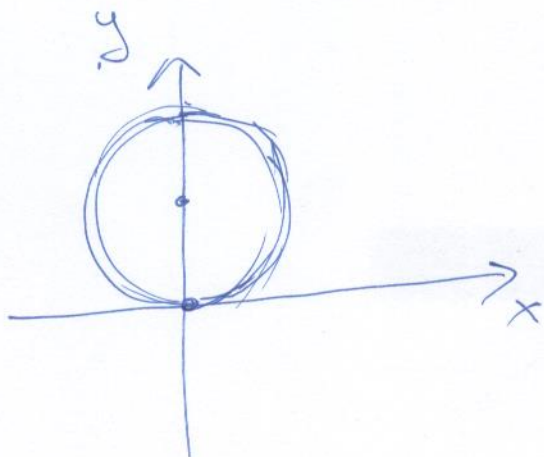
Example 1. Calculate

$$\int_L (x+y) ds,$$

when  $L$  is defined by the formula

$$L: x^2 + y^2 = 2y$$

- 7 -



We use polar coordinates:

$$x = r \cos \varphi$$

$$y = r \sin \varphi$$

Curve  $L$  is defined in polar coordinates by

$$r^2 \cos^2 \varphi + r^2 \sin^2 \varphi = 2r \sin \varphi$$

$L:$

$$r^2 = 2r \sin \varphi \Rightarrow$$

$$\boxed{\begin{array}{l} r = 2 \sin \varphi \\ 0 \leq \varphi \leq \pi \end{array}}$$

$$ds = \sqrt{(x'_{\varphi})^2 + (y'_{\varphi})^2} d\varphi$$

$$= \sqrt{(r'_{\varphi} \cos \varphi - r \sin \varphi)^2 + (r'_{\varphi} \sin \varphi + r \cos \varphi)^2} d\varphi$$

$$= \sqrt{r^2 + (r'_{\varphi})^2} d\varphi = 2 d\varphi.$$

$$\int_L (x+y) ds = 2 \int_0^{\pi} (r \cos \varphi + r \sin \varphi) d\varphi$$

$$= 4 \int_0^{\pi} (\sin^2 \varphi + \sin \varphi \cos \varphi) d\varphi = 2\pi.$$

### Curvilinear integrals of second kind

Let us consider the curve  $L$  defined in  $\mathcal{D} \subset \mathbb{R}^2$ .

Also we have a vector  $\vec{F}$  (a field of forces)

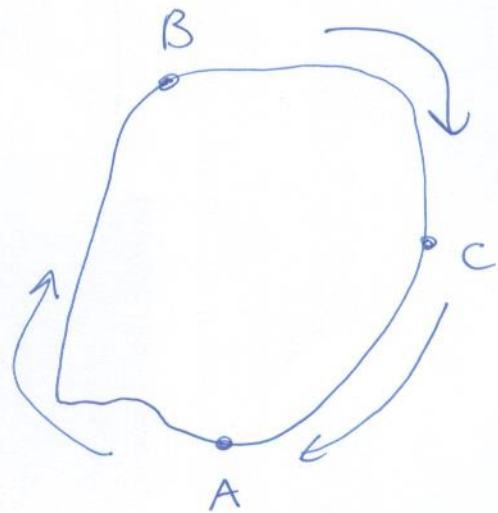
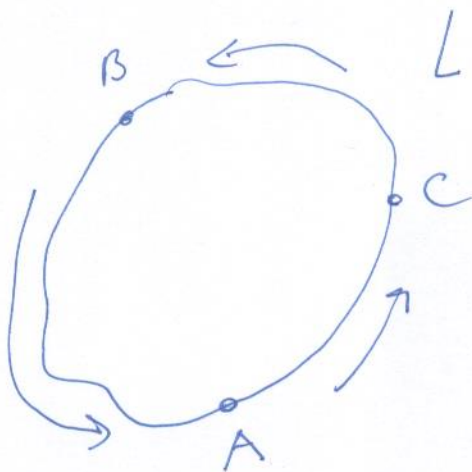
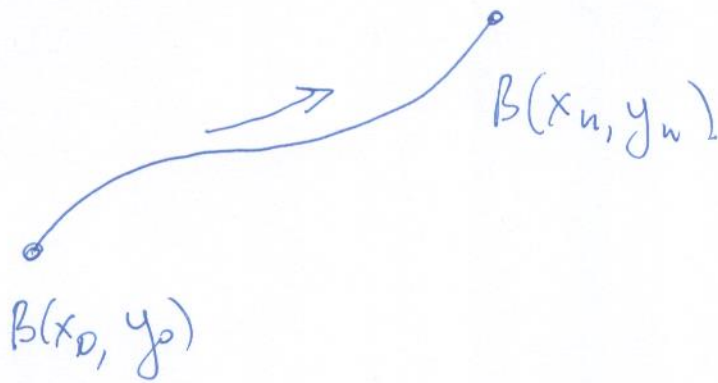
$$\vec{F} = P(x, y) \vec{i} + Q(x, y) \vec{j}$$

A material point  $M(x, y)$  is ~~now~~ moved due to influence of forces  $\vec{F}$  from a starting point of  $L$   $B(x_0, y_0)$  to the final point  $B(x_n, y_n) \in L$ .

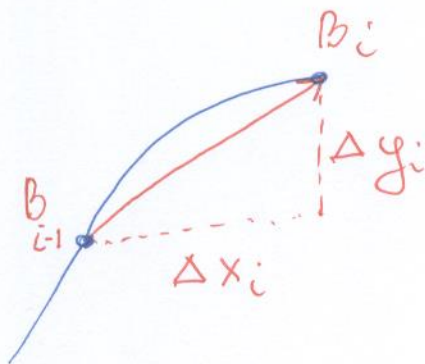


We want to calculate the work  $W$  done by force  $\vec{F}$ .

1. The orientation of the curve is given (e.g.  $B(x_0, y_0) \rightarrow B(x_n, y_n)$ ).



opposite orientation.



$$\vec{\Delta S}_i = (\Delta x_i, \Delta y_i).$$

Then 
$$W_i \approx \vec{F}(\bar{x}_i, \bar{y}_i) \cdot \Delta S_i$$
$$= P(\bar{x}_i, \bar{y}_i) \Delta x_i + Q(\bar{x}_i, \bar{y}_i) \Delta y_i$$

Let us consider some partition of  $L$  and calculate a sum

$$\sigma_\tau = \sum_{i=1}^n P(\bar{x}_i, \bar{y}_i) \Delta x_i + Q(\bar{x}_i, \bar{y}_i) \Delta y_i$$

Def. Curvilinear integral of second kind is defined by a limit:

$$\int_L P(x, y) dx + Q(x, y) dy = \lim_{\delta_\tau \rightarrow 0} \sigma_\tau.$$

If  $L$  is defined in 3D space and vector of forces is given by

$$\vec{F} = P(x, y, z) \vec{i} + Q(x, y, z) \vec{j} + R(x, y, z) \vec{k}$$

then

$$W = \int_L P(x, y, z) dx + Q(x, y, z) dy + R(x, y, z) dz$$

---

Definition . If  $L$  is a closed curve, then we use notation (here  $L$  is defined in a plane)

$$\oint_L P(x, y) dx + Q(x, y) dy$$

or in space  $\mathbb{R}^3$ :

$$\oint_L P(x, y, z) dx + Q(x, y, z) dy + R(x, y, z) dz.$$

If the orientation of  $L$  is changed then

$$\int_{AB} P(x, y) dx + Q(x, y) dy = - \int_{BA} P(x, y) dx + Q(x, y) dy.$$

## Calculation of integrals

Our aim to reduce curvilinear integrals of second kind to *definite integrals*.

Let us consider integral

$$\int_{AB} P(x, y) dx$$

A curve  $L$  is defined by parametric equations

$$x = x(t), \quad y = y(t), \quad t_0 \leq t \leq T$$

$$\int_{AB} P(x, y) dx = \int_{t_0}^T P(x(t), y(t)) x'(t) dt$$

$$\sigma_{\tau} = \sum_{i=1}^n P(\bar{x}_i, \bar{y}_i) \Delta x_i$$

$$\Delta x_i = x(t_i) - x(t_{i-1}) = x'(\tilde{t}_i) \Delta t_i$$

We can select  $(\bar{x}_i, \bar{y}_i)$  such that

$$\bar{x}_i = x(\tilde{t}_i), \quad \bar{y}_i = y(\tilde{t}_i).$$

Then

$$\sigma_T = \sum_{i=1}^n P(x(\tilde{t}_i), y(\tilde{t}_i)) x'(\tilde{t}_i) \Delta t_i.$$

By taking a limit  $\max \Delta t_i \rightarrow 0$   
we get the required formula

$$\int_{AB} P(x, y) dx = \int_{t_0}^T P(x(t), y(t)) x'(t) dt.$$

Similarly it follows that

$$\int_{AB} P(x, y) dx + Q(x, y) dy = \int_{t_0}^T (P(x(t), y(t)) x'(t) + Q(x(t), y(t)) y'(t)) dt.$$

Thus integrals exist if  $P, Q$  are continuous and  $L$  is smooth.

Example 1. Calculate

$$W_1 = \int_L xy dx + (x^2 - y^3) dy$$

from point  $O(0,0)$  till  $A(1,1)$ ,

$$L: y = x^3.$$

Parametric equation  $y = y(x)$ .

$$dy = 3x^2 dx$$

$$W = \int_0^1 x x^3 dx + \int_0^1 (x^2 - x^9) 3x^2 dx = \frac{11}{20}.$$

b)  $y = x$  defines  $L$

$$dy = dx$$

$$W_2 = \int_0^1 x^2 dx + \int_0^1 (x^2 - x^3) dx = \frac{5}{12}.$$

$$W_1 \neq W_2.$$

Example 2. Calculate

$$W = \int_L (2x + 3y^2) dx + (6xy - 1) dy$$

from point A(1,1) till point B(2,4)

when curves L are defined by:

a) a line  $y = 3x - 2$

b) a parabola  $y = x^2$

c) a curve ACB, where C(1,2).

Solution.

a)  $y = 3x - 2$       $\underline{dy = 3 dx}$

$$W = \int_1^2 (2x + 3(3x-2)^2) dx + \int_1^2 (6x(3x-2) - 1) \times 3 dx = 93$$

b)  $\underline{dy = 2x dx}$

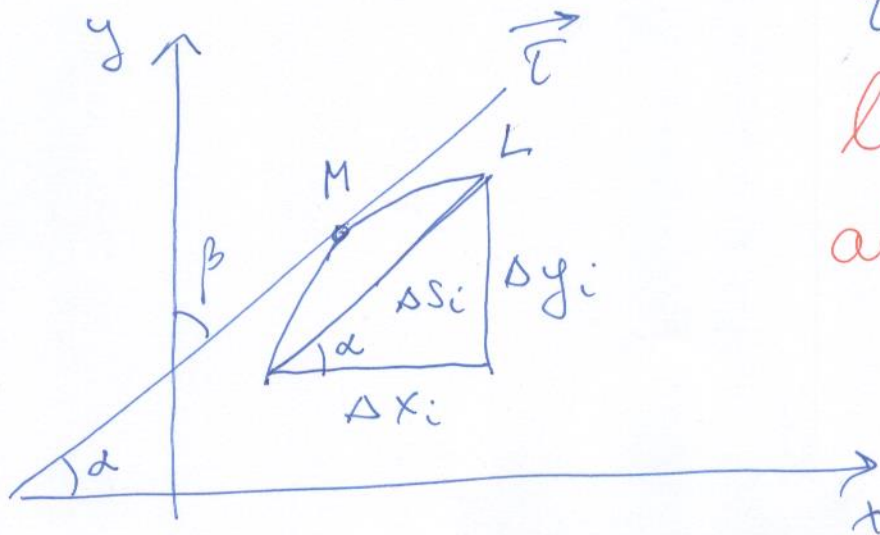
$$W = \int_1^2 (2x + 3x^4) dx + \int_1^2 (6x^3 - 1) 2x dx = 93$$

c) W = 93

!!!

The value of the integral is the same for any path  $L$  connecting points  $A$  and  $B$ .

Connection of integrals of both kinds.



$\vec{T}$  is tangent line of a curve  $L$  at a point  $M$ .

We get approximate equalities

$$\Delta x_i \approx \cos \alpha \Delta S_i$$

$$\Delta y_i \approx \cos \beta \Delta S_i$$



Take sums :

$$\sum_{i=1}^n P(\bar{x}_i, \bar{y}_i) \Delta x_i + Q(\bar{x}_i, \bar{y}_i) \Delta y_i$$

$$\approx \sum_{i=1}^n \left[ (P(\bar{x}_i, \bar{y}_i) \cos \alpha + Q(\bar{x}_i, \bar{y}_i) \cos \beta) \right] \Delta s_i$$

By taking a limit  $\Delta s_i \rightarrow 0$  we get

$$\int_L P(x, y) dx + Q(x, y) dy = \int_L (P(x, y) \cos \alpha + Q \cos \beta) ds$$

$$\alpha = \alpha(x, y), \quad \beta = \beta(x, y)$$

In the case of 3D integrals

$$\int_L P(x, y, z) dx + Q(x, y, z) dy + R(x, y, z) dz$$

$$= \int_L (P(x, y, z) \cos \alpha + Q(x, y, z) \cos \beta + R(x, y, z) \cos \gamma) ds$$

## Green's theorem

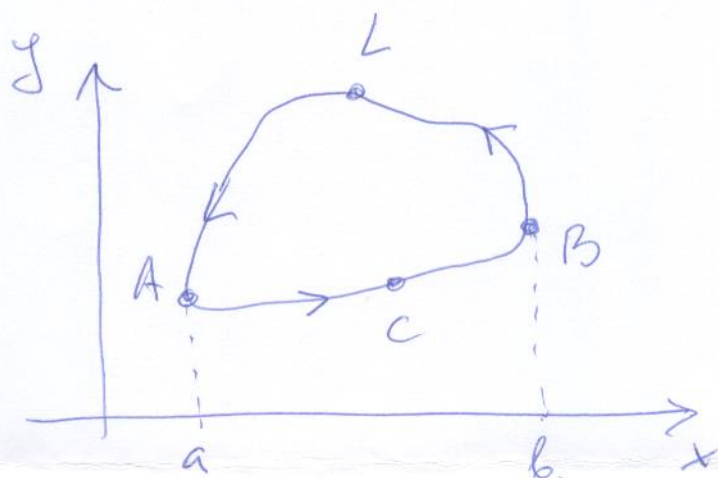
This theorem relates a line integral around a simple closed curve  $L$  to a double integral over the plane region  $D$  bounded by  $L$ .

Th. Let  $L$  be positively oriented, smooth and simple closed curve in a plane and  $D$  be the region bounded by  $L$ . If  $P(x, y)$  and  $Q(x, y)$  are functions of  $(x, y)$  defined on  $D$  and have continuous partial derivatives, then

$$\oint_L (P dx + Q dy) = \iint_D \left( \frac{\partial Q}{\partial x} - \frac{\partial P}{\partial y} \right) dx dy$$

where the path of integration along  $L$  is anticlockwise.

The curve is said to be positively oriented (or counterclockwise oriented) if one always has the curve interior to the left.



$L$  is defined by  $y = y_1(x)$  for  $ACB$

$y = y_2(x)$  for  $BLA$ .

A double integral is changed to a sequence of 1D integrals (iterated)

-20-

$$\iint_D \frac{\partial P}{\partial y} dx dy = \int_a^b dx \int_{y_1(x)}^{y_2(x)} \frac{\partial P}{\partial y} dy$$

$$= \int_a^b (P(x, y_2(x)) - P(x, y_1(x))) dx$$

$$= \int_a^b P(x, y_2(x)) dx - \int_a^b P(x, y_1(x)) dx$$

(parametric formula)

$$= \int_{AEB} P(x, y) dx \quad \neq \quad \int_{ACB} P(x, y) dx$$

$$= - \left( \int_{BEA} P(x, y) dx + \int_{ACB} P(x, y) dx \right)$$

$$= - \int_L P(x, y) dx$$

Similarly we get

$$\iint_D \frac{\partial Q}{\partial x} dx dy = \int_L Q(x, y) dy \quad \blacktriangleright$$

Example. Calculate

$$W = \oint_L xy \, dx + (x^2 + y^2) \, dy,$$

when  $L$  is a circle

$$x^2 + y^2 = 2x$$

and orientation of  $L$  is positive direction

- calculate directly ( $W = \pi$ )
- Use Green's formula and calculate a double integral.

Conclusion.

If

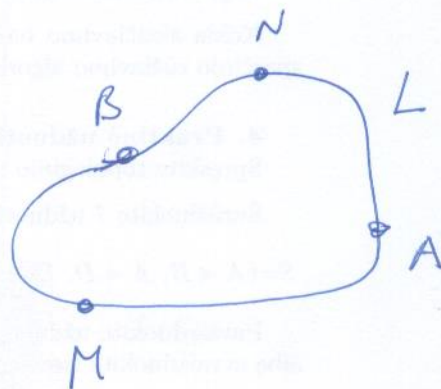
$$\oint_L P \, dx + Q \, dy = 0$$

then we get

$$\parallel \int_{MBN} P \, dx + Q \, dy$$

$$\int_{MAN} P \, dx + Q \, dy + \int_{NBM} P \, dx + Q \, dy = 0$$

$$\int_{MAN} P \, dx + Q \, dy = \int_{MBN} P \, dx + Q \, dy \quad \nabla$$



It follows from Green's theorem that

$$\oint_L P dx + Q dy = \iint_D \left( \frac{\partial Q}{\partial x} - \frac{\partial P}{\partial y} \right) dx dy.$$

For any  $L$  (and  $D$ )

$$\oint_L P dx + Q dy = 0 \Leftrightarrow \frac{\partial P}{\partial y} = \frac{\partial Q}{\partial x}$$

In our previous example we had:

$$P(x, y) = 2x + 3y^2$$

$$Q(x, y) = 6xy - 1$$

$$\frac{\partial P}{\partial y} = 6y \quad \text{and} \quad \frac{\partial Q}{\partial x} = 6y$$